Zuo Jia

Education

Nanyang Technological University (NTU)

Master of Science: Computer Control and Automation School of Electrical and Electronic Engineering

GPA: 5.0/5.0

Harbin Institute of Technology at Weihai (HIT) Major: Measurement and Control Technology and Instruments Bachelor of Engineering GPA: 84.22/100 **IELTS: 6.5**

Project Experience

Deep Diffusion Models for Vital Signal Estimation – Currently Research Sep 2023 – Present Supervised by Dr. Jianfei Yang and Prof. Lihua Xie

Developing a Transformer-based encoder to extract useful information from mmRadar raw data.

Applying stable diffusion for noise reduction, aiming to isolate pure human vital signals (respiratory and pulse).

Reinforcement Learning Solve Distributed Flow-Shop Scheduling Problem

- Solved Distributed Flow-Shop Scheduling Problem (DFSP) using value based reinforcement learning (RL) algorithm, which is my undergraduate thesis at HIT.
- Electronic Control Software Architecture Project based on RT-Thread
- Designing the entire embedded software for a robot, including two-axis gimbal control, embedded drive development, and sophisticated algorithms enabling remote-controlled operations such as bombing, movement, and vision-based automatic targeting and engagement etc..
- Contributed to the RT-Thread community by fixing critical CAN and PWM driver bugs.

Motor Intelligent Control Board Software Development Project

 Developed algorithm for Motor Intelligent Control Board, enabling automatic calibration of initial position, angle, and speed loops. Implemented master-slave auto-processing and integrated motor stall and disconnection alarms.

2022 XbotPark Smart Product Innovation Boot Camp

- Developed demos for two startup ideas as a Full Stack Engineer.
- Gained expertise in design thinking, user research, smart hardware design, and product management, etc..

HIT Mathematical Competition Team

• Led a team to participate in four national-level mathematical contests, used Python, Mathematica, and SPSS for modelling.

Anti-jamming Adaptive Exposure Algorithm Project

 Developed algorithms to automatically identify and remove large light spots and use PI controller to achieve automatic exposure for large target detection.

Self-Balanced Two-wheeled Smart Car Project in the National Intelligent Car Race Nov 2019 – Sep 2020

- Engineered balance and motion control algorithms using a PID cascade controller and Kalman filter with six-axis sensors for car stability.
- Developed electromagnetic tracking and adaptive road condition algorithms for navigating roundabouts, sharp turns, and ramps.

Nov 2019 - Sep 2020 Smartwatch Project in the National Undergraduate Electronics Design Contest

 Implemented features including body temperature monitoring, step counting, automatic screen lighting upon wrist lift, and sleep posture detection using an anti-bright screen algorithm.

Professional Skills

Programming language: Python, C programming Model (Based on PyTorch): Transformer, Diffusion Platform: STM32, MSP430, STC, LPC, Linux Software: Skilled with Keil, IAR, LabView, SPSS; familiar with MATLAB, Webots, Solidworks Embedded Real-Time Systems (RTOS): RT-Thread

Jul 2021 – Feb 2022

Sep 2020 – May 2022

Jul 2022 – Apr 2022

Sep 2020 - Nov 2021

Jan 2021 – Apr 2021

Sep 2019 - Jun 2023

Aug 2023 - Present

Weihai, China

Singapore

Oct 2022 – May 2023

HERO Competitive Robot Team – Team Leader HIT 718 Smart Car Laboratory - Team Leader

Honors

 1st Prize in the Final Round of the National College Students' ROBOMASTER 2022 Infantry Robotic Competition 2nd Prize in the Final Round of the National College Students' ROBOMASTER 2022 Robotic Competition 2nd Prize in the Final Round of the National College Students' ROBOMASTER 2021 Robotic Competition 2nd Prize in 2021 Higher Education Cup National Undergraduate Mathematical Contest in Modeling 	08/2022 08/2022 08/2021 11/2021
Regional-Level Awards	
 1st Prize in the Eastern Division of the National College Students' ROBOMASTER 2022 Robotic Competition 1st Prize in the Northern Division of the National College Students' ROBOMASTER 2021 Robotic Competition 	08/2022 08/2021
Provincial-Level Awards	
 1st Prize in the 11th Shandong University Student Science and Technology Festival - Science and Technology Museu Creativity and Production Design Competition 2nd Prize in the National College Students Mathematical Contest in Modeling, Shandong Division 2nd Prize in the Shandong Division of National Undergraduate Electronic Design Competition 	m Exhibit 11/2019 10/2020 10/2020
Other Honors and Scholarships	
 Zeshi Scholarship (Top 10 in HITwh) Junior Product Manager, rewared by 2022 XbotPark Smart Product Innovation Robot Camp Second-class Scholarship, sponored by Harbin Institute of Technology (Weihai), 2020-2021 Spring Semester Outstanding individual in science and technology, issued by School of Information Science and Engineering, Harbin of Technology (Weihai) Outstanding Student Leader, rewared by Harbin Institute of Technology (Weihai) Science and Technology Innovation Scholarship, sponored by Harbin Institute of Technology (Weihai), 2019-Semester 	12/2020 12/2020

Related Courses

NTU

- \circ Computer Control and Automation (5.0/5.0)
- \odot Linear System (5.0/5.0)
- \circ Machion Vision (5.0/5.0)
- System Analysis (5.0/5.0)

HIT

- Analogue Electronic Technology Experiment (94)
- Advanced Project-driven Electronic Technology Experiment (93)
- College Computer (91)
- C Language Programming (96)
- Error Theory and Data Processing (95)
- MCU Application Expansion Experiment (95)
- Single-chip Microcomputer Principle and Interface Technology (95)
- Virtual Instrument Software Design (95)
- Electronic Technology Practice (96)
- Automation Measurement Technology (92)
- Fiber-Optic Communications Technology (92)